

Rotary unit for optical parts

Hollow Shaft Motor

Summary

- Coreless type hollow motor, can rotate from super low speed to high speed.
- Design and manufacture the mounting flange as being able to put on the optical components.
- High precision jitter accuracy is realized with PLL (phase) control driver.
- Can correspond various sensor · sensorless. (Supply dedicated driver)

■ Feature

- As mechanism of the motor, flat type for thin type, cylindrical type for high speed specification,
 Can selected with your application.
- Supply including attachment of light source and optical parts.
- Depend optical parts, the rotor shape can be changed. (from one article to customize)
- Can be mounted on the tip of the robot by making it smaller and lighter.
- · Built-in (diret attachment) of optical encoder, realized high precision and high resolution positioning. (1 second or less)
- · Adopting the digital servo driver, can be easily controlled from the PC, and possible connect with.
- For motor without encoder, holl sensors, prepare sensorless driver. (However, about 1500 rpm or more)
- Sensorless driver specification, improvement of reducing the number of lines.

Application

Laser measuring instrument, laser processing machine (cutting, welding, drilling, microfabrication etc.), spectrometer, distance measuring device (LIDAR), medical measurement etc.

■ Motor model format



	Mark	No	Classification	Description
1	НМ	НМ	Hollow	Motor Type (Hollow Shaft)
2	С	C F I	Cylinder Flatness Iron core	Mechanism of motor
3	AA	Value		Optical size · Hollow diameter[mm]
4	ВВ	Value		Motor length[mm] Flange, shaft length including cover

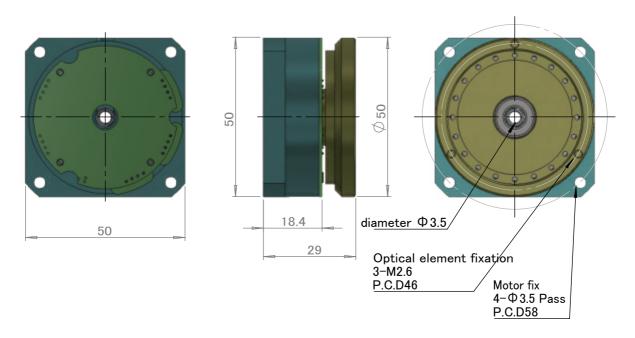
		Mark	No	Classification	Descri	ption
		Н	L	Slow speed	Speed[rpm]	100~2000
ı	5		М	Medium speed		1000~6000
ı			Н	high speed		5000~
ı		E	E* *	Encoder	Sensor type	1800pls E18
ı	6		F**	FG sensor		12pls F12
ı			Z1	PG output		1pls Z1
ı	7	XXX	Value	Rotor Shape	customize, seria	al No.(001~999)

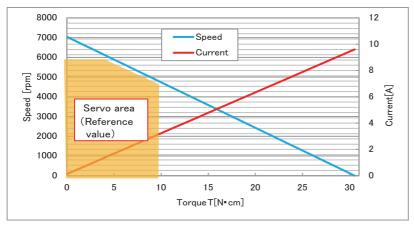
Standard product list

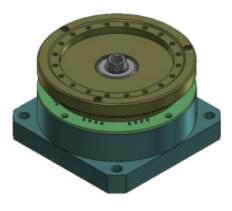
Motor model number	Motor mechanism	Hollow diameter[mm]	Outer Diameter[mm]	Lengh[mm]	Speed[rpm]	Page
HMF0429ME10		4	50	29	6,600	2
HMF0931HF12	Flatness	9	55	31	12,000	3
HMF2240ME20		22	82	40	3,600	4
HMC2473HZ1		24	98	73	14,000	5
HMC2659HZ1	Cylinder	26	73	59	14,000	6
HMC2850HE18		28	75	50	9,000	7

- We recommend installing holder (optical parts, etc.) and adjusting the balance if over thousand rpm.)
 (Balance correction will be require cost)
- 💥 We propose and select the suitable driver (phase · accumulation pulse, analog etc) according to customer's application.
- * Possible to change shape of the motor shaft and incorporate the optical parts directly into a compact shape.
- We change the bearing into air bearing as the large diameter, and guarantee the high rotation accuracy (Non-Repeatable Run-out).

HMF0429(L,M,H) E10 Type (Flat type: medium to high speed type)







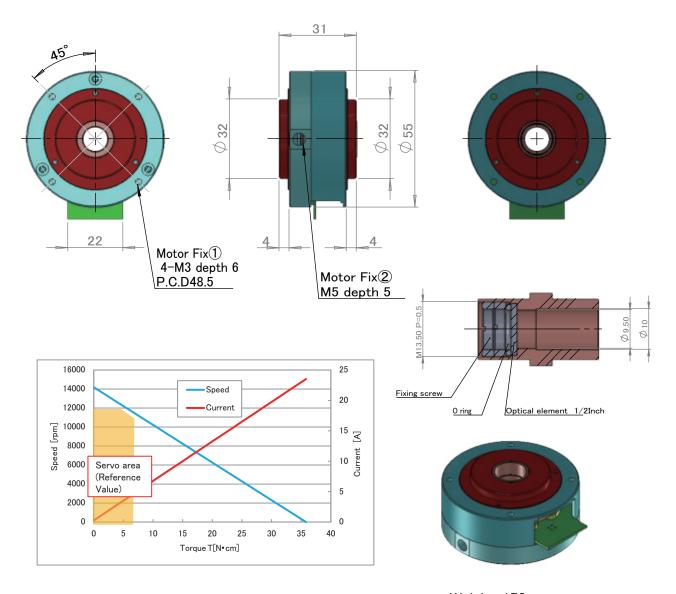
Weight: 130gLoad: 50g

Motor Specification

	Multiplier				
	×1	× 4	× 20	× 200	
モータ型番	HMF04	29HE10	HMF0429ME10	HMF0429LE10	
Resolution[CPR]	1,080	4,320	21,600	216,000	
Resolution[deg/pls]	0.33	0.083	0.017	0.0017	
MAX Speed[rpm]	6,600	6,600	5,500	550	
Torque constant[N•cm/A]	1.6				
Power Supply	r Supply DC24V (Reference: 6,000rpr			0.3A)	

- Motors used for LIDAR application.
- •Integrated analog driver(Variable speed with voltage).
- •Adopte compact optical encoder, output by free multiplication.

HMF0931(M,H) F12 Type (Flat type: High speed type)



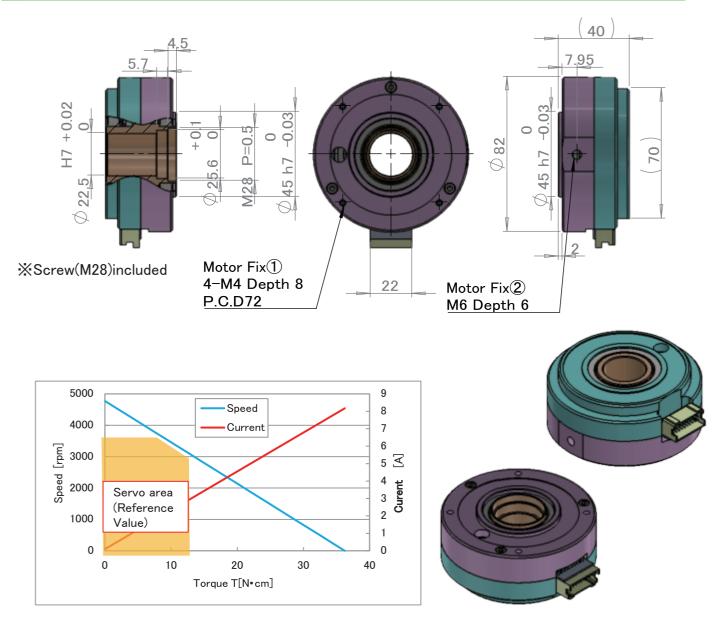
Weight: 170gLoad: 15g

Motor Specification

	Medium speed ⇔ High speed	
Motor Type	HMF0931MF12	HMF0931HF12
MAX Speed[rpm]	6,000	12,000
Torque constant[N•cm/A]	2.4	1.2
FG output[pls/r]	12	
Power supply	DC24V(Reference 6,000rpm、0.3A)	

- Hollow shaft motor with measures against grease scattering during high speed rotation.
- High speed rotation with low current, low vibration, low noise.
- *Built-in half-inch optical element realizes thin type.
- Mounted on optical surface plate with side M6 screw hole.
- •Low jitter is guaranteed with a dedicated driver for PLL(phase)control.

HMF2240(L,M) E20 Type (Flat type: Low to medium speed type)



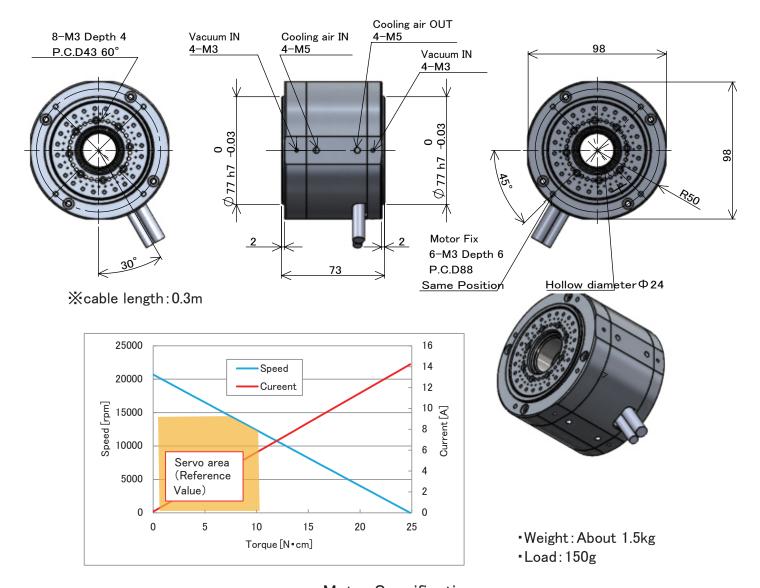
•Weight: 400g •Load: 70g

Motor Specification

	Multiplier				
	×1	× 4	× 20	× 200	
Motor Type	HMF2240ME20			HMF2240LE20	
Resolution[CPR]	2,000	8,000	40,000	400,000	
Resolution[deg/pls]	0.18	0.045	0.009	0.0009	
MAX Speed[rpm]	3,600	3,600	3,000	300	
Torque constant[N•cm/A]	1.6				
Power supply	24V (Reference: 3,000rpm, 0.8A)				

- •Realized thin type of incorporating reflective optical encoder inside
- •One inch optical element can be mounted inside case with thickness of 40mm.
- •Mounted on optical surface plate with side M6 screw hole.
- High precision position by combining with a digital servo driver.

HMC2473(M,H) Z1 Type (Cylinder type: High speed type)



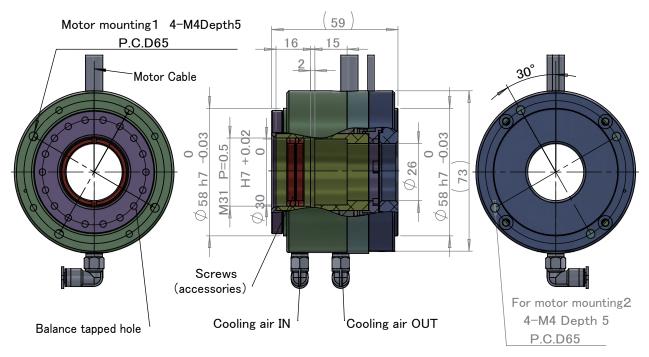
Motor Specification

	Medium speed <	⇒ High speed
Motor Model	HMC2473MZ1	HMC2473HZ1
MAX Speed[rpm]	6,000	14,000
Torque constant[N • cm/A]	2.4	1.8
PG output [pls/r]	1	
Power supply	DC24~48V(Reference: 14,000rpm、3A)	

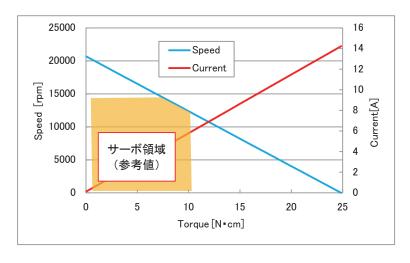
く特長>

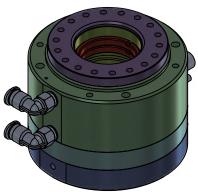
- Supply beam rotator with two wedge prisms.
- The phase of wedge prism can be varied in increments of 10°
- Measures against scattering of grease · With cooling mechanism.
- •Ideal for laser welding applications at high speed rotation.
- The rotational position can be detected with 1 pulse per cyple (PG output).
- *Constant speed is secured by combining sensorless driver with PLL (phase).

HMC2659(M,H) Z1 Type (Cylinder type: High speed type)



X Cable length: 0.3m





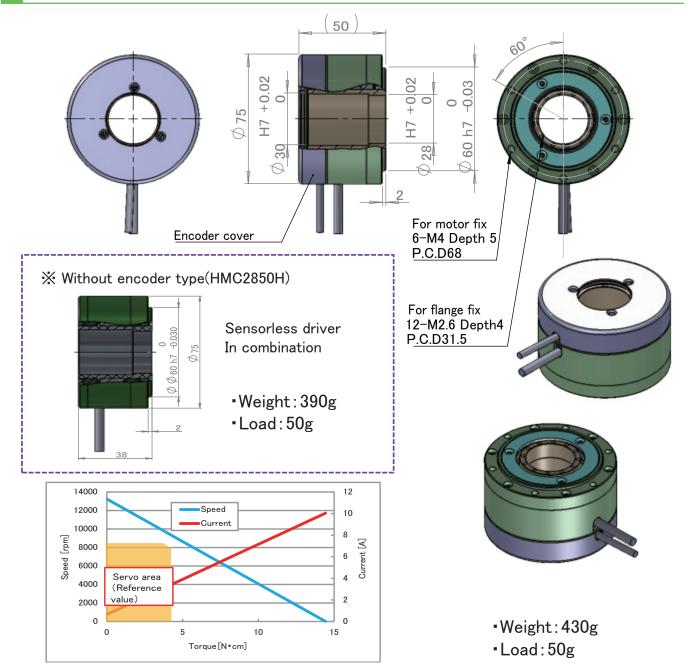
Weight: 580gLoad: 50g

Motor Specification

	Medium speed <	⇒ High Speed	
Motor Type	HMC2659MZ1	HMC2659HZ1	
MAX Speed[rpm]	6,000	14,000	
Torque constant[N·cm/A]	2.4 1.8		
PG output [pls/r]	1		
Power Supply	DC24~48V(Reference: 14,000rpm、3A)		

- •1 inch optical element can be mounted inside the cabine.
- •Flange type hollow diameter Φ30 possible. (option)
- Measures against scattering of grease · With air cooling mechanism.
- The rotational position can be detected with 1 pulse per cycle output (PG output).

HMC2850 (M,H) E18 Type (Cylindrical, medium to high speed type)



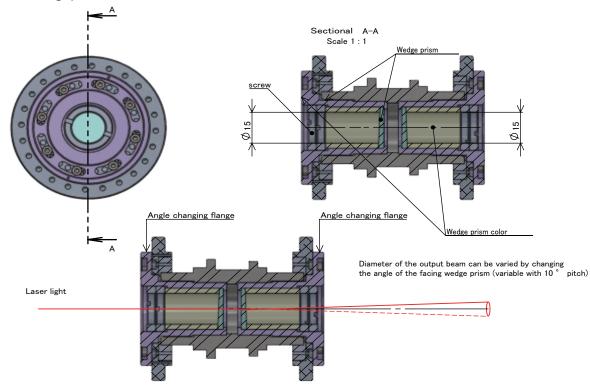
Motor Specification

	Medium speed <i>⇐</i>	High speed	Without sensor	
Motor Type	HMC2850ME18	HMC2850HE18	HMC2850H	
MAX Speed[rpm]	4,000 9,000		14,000	
Torque constant[N•cm/A]	3.5	1.5	1.2	
Resolution[CPR]	1,8	_		
Power supply	DC24~36V(Reference: 9,000rpm, 2A / 14,000rpm, 3A)			

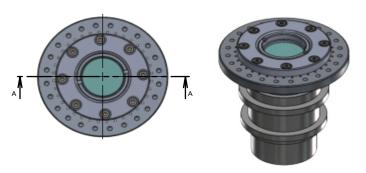
- By attaching one inch flange, optical element can be mounted.
- Allows mounting optical elements by changing rotor shape.(option)
- By adopting a high response frequency encoder, high speed and high precision are compatible.
- Digital servo driver prepared for high positioning control.

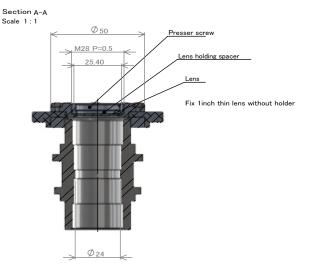
Application of optical element mounting

1. Application of wedge prism



2. Application of polarizing plate

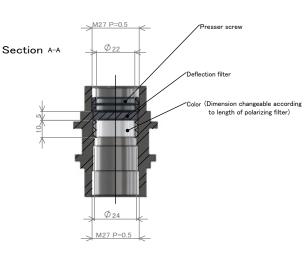






3. Wavelength plate application





Tel: +81-45-370-8010 Fax: +81-45-370-8015 Email: info@technohands.co.jp